



Comp. Sc. Dpt.

Computing expectations over p-boxes : two views (LP and RS) of the same problem

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Problem statement

- information on r.v. X modeled by a p-box $[E, \bar{F}]$
- lower ($\underline{\mathbb{E}}$) and upper ($\bar{\mathbb{E}}$) exp. on continuous function $h(X)$:

$$\underline{\mathbb{E}}(h) = \inf_{F \leq F \leq \bar{F}} \int_{\mathbb{R}} h(x) dF, \quad \bar{\mathbb{E}}(h) = \sup_{F \leq F \leq \bar{F}} \int_{\mathbb{R}} h(x) dF \quad (1)$$

- Find optimal distribution F ($E(x) \leq F(x) \leq \bar{F}(x)$) for which $\underline{\mathbb{E}}, \bar{\mathbb{E}}$ are reached.

Linear programming (LP) general view

- Approximate F by N points $F(x_i), i = 1, \dots, N$ and solve

$$\underline{\mathbb{E}}^*(h) = \inf \sum_{k=1}^N h(x_k) z_k \quad \text{or} \quad \bar{\mathbb{E}}^*(h) = \sup \sum_{k=1}^N h(x_k) z_k$$

subject to

$$z_i \geq 0, \quad i = 1, \dots, N, \quad \sum_{k=1}^N z_k = 1, \\ \sum_{k=1}^i z_k \leq \bar{F}(x_i), \quad \sum_{k=1}^i z_k \geq E(x_i), \quad i = 1, \dots, N.$$

- $\underline{\mathbb{E}}^*, \bar{\mathbb{E}}^*$ are approximations of $\underline{\mathbb{E}}, \bar{\mathbb{E}}$
- If N high, computation costs increase, and if N low, approximations can be bad ones

Random set (RS) general view

- Mapping Γ from prob. space to power set $\wp(X)$ of a space X
- Here, mapping from $[0, 1]$ with Lebesgue measure to measurable subsets of \mathbb{R} .

Given continuous p-box $[E, \bar{F}]$
 $A_\gamma = [a_{*\gamma}, a_\gamma^*]$ is the set s.t.

$$a_{*\gamma} := \sup\{\bar{F}(x) < \gamma\} = \bar{F}^{-1}(\gamma), \\ a_\gamma^* := \inf\{E(x) > \gamma\} = E^{-1}(\gamma),$$

- P-box $[E, \bar{F}]$ equivalent continuous random set with unif. density on $[0, 1]$ and

$$\Gamma(\gamma) = A_\gamma = [a_{*\gamma}, a_\gamma^*], \quad \gamma \in [0, 1].$$

- Computing $\underline{\mathbb{E}}, \bar{\mathbb{E}}$ of h can be reformulated

$$\underline{\mathbb{E}}(h) = \int_0^1 \inf_{x \in A_\gamma} h(x) d\gamma, \quad \bar{\mathbb{E}}(h) = \int_0^1 \sup_{x \in A_\gamma} h(x) d\gamma. \quad (2)$$

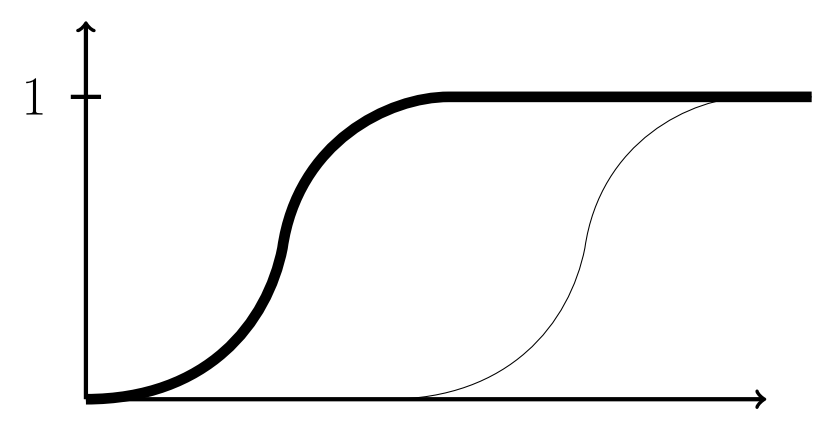
- Solution easily approximated by discretizing p-box on finite number of levels γ_i . Finding $\inf(\sup)$ on many levels can be difficult, and choosing too few γ_i or poor heuristics can again lead to bad approximations.

- For both approaches, need to find efficient AND reliable algorithms to compute $\underline{\mathbb{E}}, \bar{\mathbb{E}}$.
- Here, we interest ourselves to the case where h behavior is partially known

The easy case of monotonic functions

- If h is non-decreasing in \mathbb{R} , then we have :

$$\underline{\mathbb{E}}(h) = \int_{\mathbb{R}} h(x) dF, \quad \bar{\mathbb{E}}(h) = \int_{\mathbb{R}} h(x) d\bar{F} \quad (3)$$



Optimal F for non-decreasing h in bold

One dimension, One maximum

- h has one maximum at point a and is increasing (decreasing) in $(-\infty, a]$ ($[a, \infty)$).

Unconditional expectations

- upper and lower expectations of $h(X)$ on $[E, \bar{F}]$ are

$$\bar{\mathbb{E}}(h) = \int_{-\infty}^a h(x) dF + h(a) [\bar{F}(a) - E(a)] + \int_a^{\infty} h(x) d\bar{F} \quad (4)$$

$$\underline{\mathbb{E}}(h) = \int_{-\infty}^{\bar{F}^{-1}(\alpha)} h(x) d\bar{F} + \int_{\bar{F}^{-1}(\alpha)}^{\infty} h(x) dE \quad (5)$$

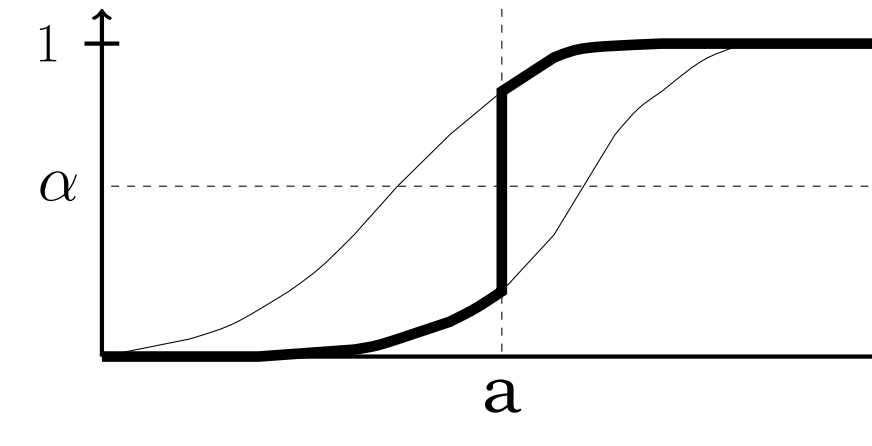
or, equivalently

$$\underline{\mathbb{E}}(h) = \int_0^{E(a)} h(a_\gamma^*) d\gamma + [\bar{F}(a) - E(a)] h(a) + \int_{\bar{F}(a)}^1 h(a_{*\gamma}) d\gamma \quad (6)$$

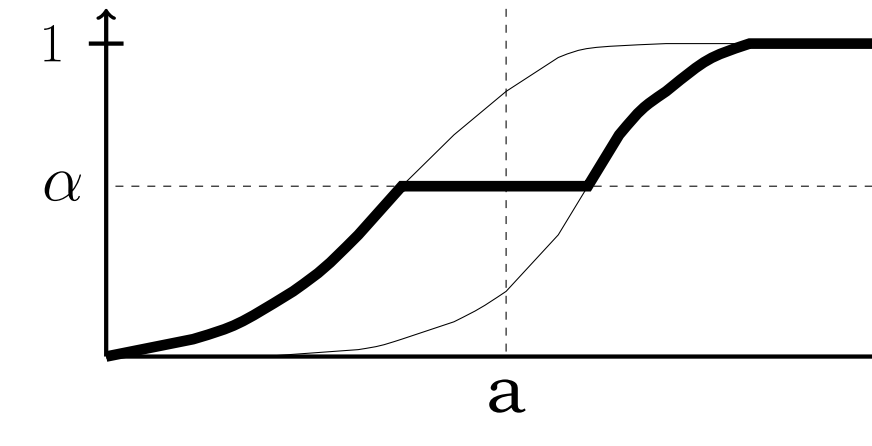
$$\bar{\mathbb{E}}(h) = \int_0^\alpha h(a_{*\gamma}) d\gamma + \int_\alpha^1 h(a_\gamma^*) d\gamma, \quad (7)$$

where α is one of the solution of the equation

$$h(\bar{F}^{-1}(\alpha)) = h(E^{-1}(\alpha)). \quad (8)$$



Optimal F for $\bar{\mathbb{E}}(h)$ (vert. jump)



Optimal F for $\underline{\mathbb{E}}(h)$ (hor. jump)

- LP approach suggest to analytically find the level α , or to approximate solution by scanning different values of α .
- Following formula derived with the RS approach

$$\underline{\mathbb{E}}(h) = \int_0^{E(a)} h(a_{*\gamma}) d\gamma + \int_{E(a)}^{\bar{F}(a)} \min(h(a_{*\gamma}), h(a_\gamma^*)) d\gamma + \int_{\bar{F}(a)}^1 h(a_\gamma^*) d\gamma$$

shows that approximation (either outer or inner) by discretization requires at most 2 computations per discretized levels, if α is unknown.

Conditional expectations

- We suppose that the event $B = [b_0, b_1]$ has been observed. Lower and upper conditional expectations under B are computed as follows :

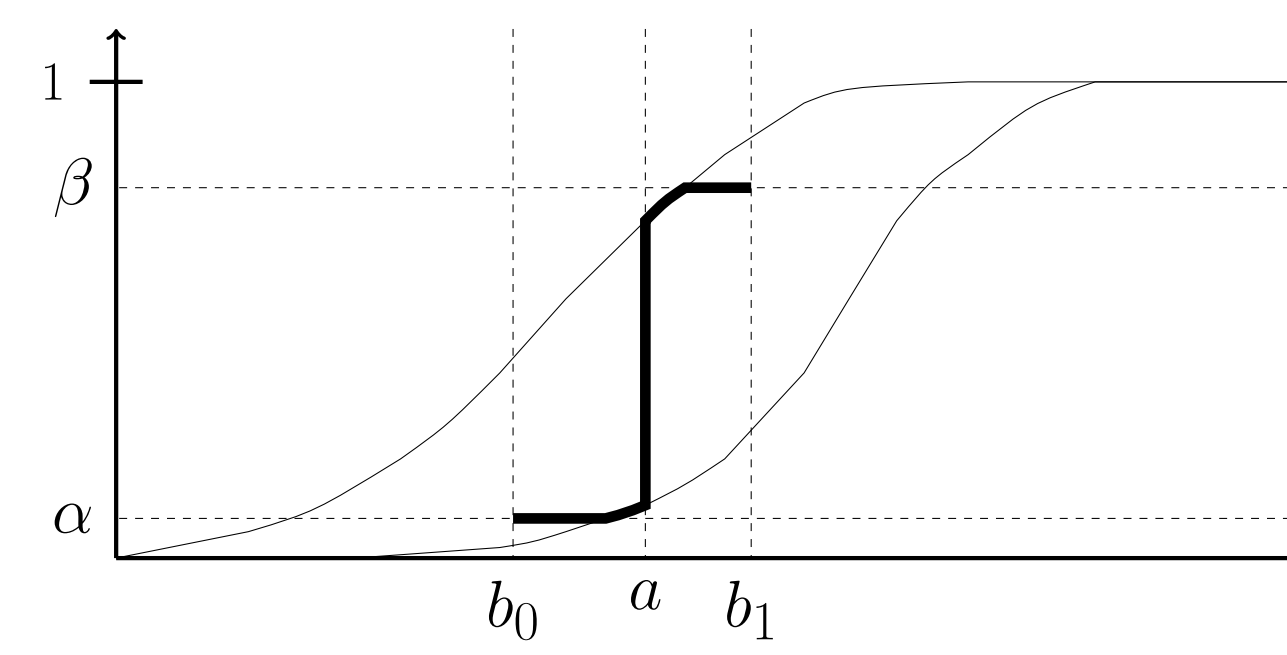
$$\underline{\mathbb{E}}(h|B) = \inf_{F \leq F \leq \bar{F}} \frac{\int_{\mathbb{R}} h(x) I_B(x) dF}{\int_{\mathbb{R}} I_B(x) dF}, \quad \bar{\mathbb{E}}(h|B) = \sup_{F \leq F \leq \bar{F}} \frac{\int_{\mathbb{R}} h(x) I_B(x) dF}{\int_{\mathbb{R}} I_B(x) dF}.$$

In the case of h having one maximum, these formulas become

$$\bar{\mathbb{E}}(h|B) = \sup_{\frac{F(b_0) \leq \alpha \leq \bar{F}(b_0)}{F(b_1) \leq \beta \leq \bar{F}(b_1)}} \frac{1}{\beta - \alpha} \Psi(\alpha, \beta), \quad \underline{\mathbb{E}}(h|B) = \inf_{\frac{F(b_0) \leq \alpha \leq \bar{F}(b_0)}{F(b_1) \leq \beta \leq \bar{F}(b_1)}} \frac{1}{\beta - \alpha} \Phi(\alpha, \beta),$$

with

$$\Psi(\alpha, \beta) = \int_{\alpha}^{\beta} \sup_{x \in (A_\gamma \cap B)} h(x) d\gamma, \quad \Phi(\alpha, \beta) = \int_{\alpha}^{\beta} \inf_{x \in (A_\gamma \cap B)} h(x) d\gamma.$$



Optimal F for $\bar{\mathbb{E}}(h|B)$

- Numerator and denominator play opposite role in the evolution of expectations (e.g. for the upper one, both increase with the value of $\beta - \alpha$).
- The main problem is to find the couple (α, β) for which extremal expectations are reached. One possibility is to start with $(\alpha, \beta) = (F(b_0), \bar{F}(b_1))$ and then to shrink this interval.

Many dimensions, One global maximum

- We assume $h(X, Y)$ is a function from $\mathbb{R}^2 \rightarrow \mathbb{R}$. Our uncertainty model about X, Y becomes a bivariate p-box

$$F(x, y) \leq F(x, y) \leq \bar{F}(x, y), \quad \forall (x, y) \in \mathbb{R}^2.$$

- h has one global maximum at point (x_0, y_0) and is non-increasing in every direction from (x_0, y_0) .
- We study how upper/lower expectations can be computed under various assumptions of independence.

Random set corresponding to the marginal p-box of Y given by sets $B_\kappa = [b_{*\kappa}, b_\kappa^*]$ s.t.

$$b_{*\kappa} := \sup\{y \in [b_{inf}, b_{sup}] : \bar{F}(y) < \kappa\} = \bar{F}^{-1}(\kappa), \\ b_\kappa^* := \inf\{y \in [b_{inf}, b_{sup}] : E(y) > \kappa\} = E^{-1}(\kappa).$$

Case of strong independence (LP)

- If h separable (i.e. $h(X, Y) = h_1(X)h_2(Y)$), then under strong independence, $\underline{\mathbb{E}}(h) = \underline{\mathbb{E}}(h_1) \cdot \underline{\mathbb{E}}(h_2)$ and $\bar{\mathbb{E}}(h) = \bar{\mathbb{E}}(h_1) \cdot \bar{\mathbb{E}}(h_2)$.
- If h not separable, then, under our assumptions and by LP approach, we get the formula

$$\bar{\mathbb{E}}(h(X, Y)) = \sup_{E_2 \leq F_2 \leq \bar{F}_2} \int_{\mathbb{R}} \bar{\mathbb{E}}(h(X, z)) dF_2(z) = \sup \xi(y_0) [\bar{F}_2(y_0) - E_2(y_0)] \\ + \int_{-\infty}^{y_0} \sup \xi(z) dE_2(z) + \int_{y_0}^{\infty} \sup \xi(z) d\bar{F}_2(z)$$

where

$$\sup_{E_1 \leq F_1 \leq \bar{F}_1} \xi(z) = h(x_0, z) [\bar{F}_1(x_0) - E_1(x_0)] + \int_{-\infty}^{x_0} h(x, z) dE_1 + \int_{x_0}^{\infty} h(x, z) d\bar{F}_1.$$

- This explicit formula comes down to concentrate probability mass on (x_0, y_0) and is similar to the one obtained for the univariate case.

- Formula obtained for lower expectation is

$$\underline{\mathbb{E}}(h(X, Y)) = \inf_{E_2 \leq F_2 \leq \bar{F}_2} \int_{\mathbb{R}} \underline{\mathbb{E}}(h(X, z)) dF_2(z) \\ = \int_{-\infty}^{\bar{F}_2^{-1}(\beta)} \int_{-\infty}^{\bar{F}_1^{-1}(\alpha_z)} h(x, z) d\bar{F}_1 d\bar{F}_2 + \int_{-\infty}^{\bar{F}_2^{-1}(\beta)} \int_{\bar{F}_1^{-1}(\alpha_z)}^{\infty} h(x, z) dE_1 d\bar{F}_2 \\ + \int_{\bar{F}_2^{-1}(\beta)}^{\infty} \int_{-\infty}^{\bar{F}_1^{-1}(\alpha_z)} h(x, z) d\bar{F}_1 dE_2 + \int_{\bar{F}_2^{-1}(\beta)}^{\infty} \int_{\bar{F}_1^{-1}(\alpha_z)}^{\infty} h(x, z) dE_1 dE_2.$$

where α_z is a solution of equation $h(\bar{F}_1^{-1}(\alpha), z) = h(E_1^{-1}(\alpha), z)$ and β solution of $\underline{\mathbb{E}}(h(X, E_2^{-1}(\beta))) = \underline{\mathbb{E}}(h(X, \bar{F}_2^{-1}(\beta)))$.

- Again, "transitions" levels α_z, β have to be found, most of the time by numerical approximations.
- For a n dimensional function with one global maximum, n such levels must be found to compute lower expectation.

Case of random set independence (RS)

Given marginal random sets, we have

$$\underline{\mathbb{E}}(h) = \int_0^1 \int_0^1 \inf_{(x, y) \in [B_\kappa \times A_\gamma]} h(x, y) d\kappa d\gamma, \quad \bar{\mathbb{E}}(h) = \int_0^1 \int_0^1 \sup_{(x, y) \in [B_\kappa \times A_\gamma]} h(x, y) d\kappa d\gamma,$$

- Again, solution can be (outer or inner) approximated by discretized levels, the main difficulty being to find the \inf, \sup (here, at most 4 computations are needed per discretized levels)
- From a numerical standpoint, RS ind. equivalent to 1st order Monte-carlo sim. where A_γ, B_κ are randomly sampled.
- Interest : random set independence computationally attractive, while result is an outer approximation of results in case of strong and epistemic independence.

Case of unknown interaction

- Given random set marginals, unknown interaction is equivalent to consider every possible joint random sets having those for marginals.
- Method : approximate $[E, \bar{F}]_X \cdot [E, \bar{F}]_Y$ with sets $A_{\gamma_i}, B_{\kappa_j}$ ($i, j = 1, \dots, n$) and where all sets have equal weights. Then compute (for an approximation of lower expectation)

$$\underline{\mathbb{E}}^*(h) = \inf_{\Gamma_{\gamma, \kappa} \in \Gamma_{\gamma, \kappa}^*} \sum_{\gamma \in \Gamma_{\gamma, \kappa}} \inf_{y \in B_{\kappa_j}} h(x, y) m_{\Gamma_{\gamma, \kappa}}(A_{\gamma_i} \times B_{\kappa_j})$$

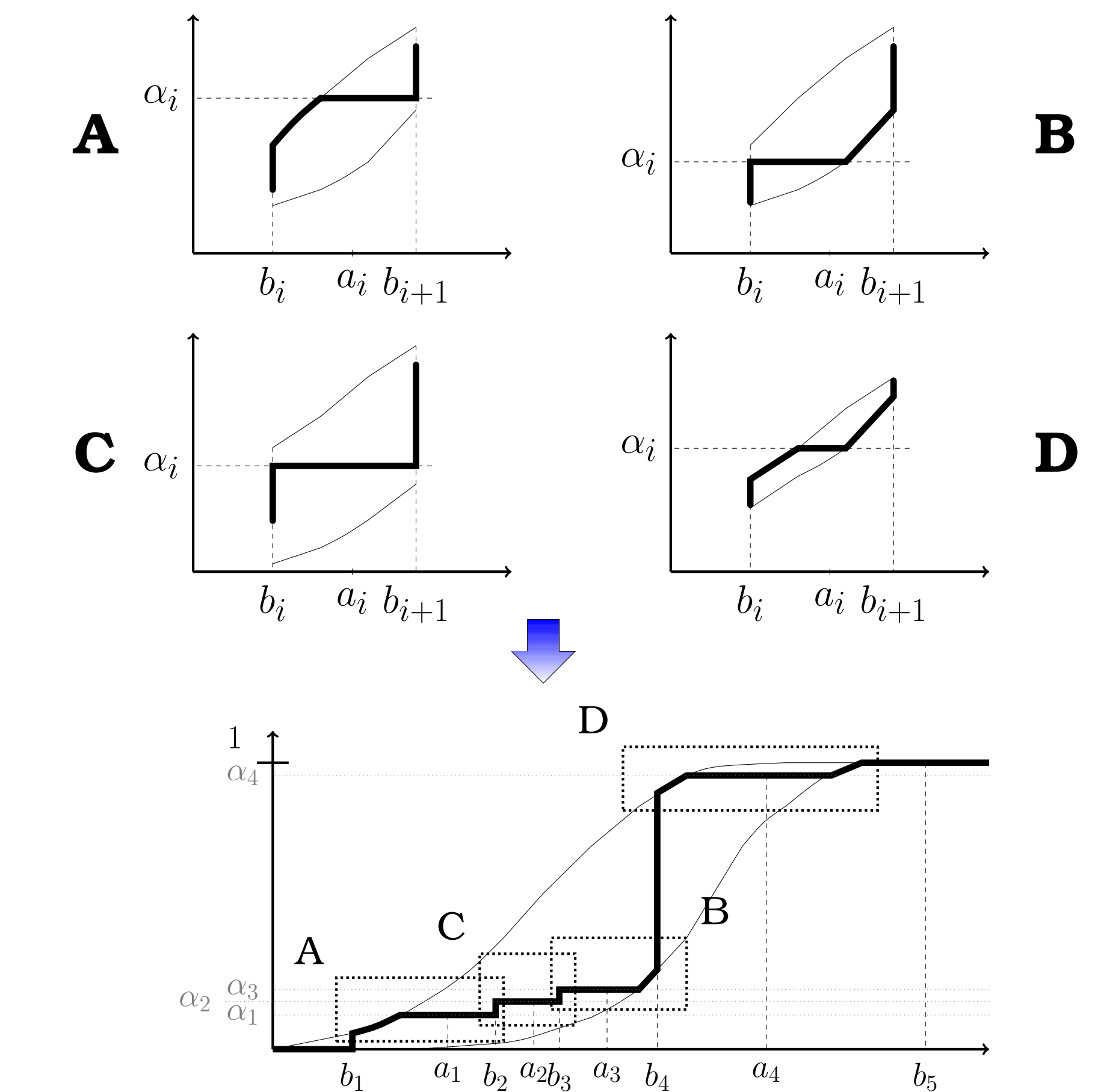
subject to

$$\sum_{j=1}^n m_{\Gamma_{\gamma, \kappa}}(A_{\gamma_i} \times B_{\kappa_j}) = m_{\Gamma_{\gamma}}(A_{\gamma_i}), \quad \sum_{i=1}^n m_{\Gamma_{\gamma, \kappa}}(A_{\gamma_i} \times B_{\kappa_j}) = m_{\Gamma_{\kappa}}(B_{\kappa_j}),$$

where $\Gamma_{\gamma, \kappa}^*$ is the set of joint random sets. $\bar{\mathbb{E}}^*(h)$ is computed by replacing \inf with \sup .

One dimension, many extrema

- h has alternate local maxima (a_i) and local minima (b_i).
- LP approach shows that optimal F reaching $\underline{\mathbb{E}}(h)$ is a combination of four different local subcases that are part of a large LP problem.



Example of Optimal F with general h which extrema are known

- These four subcases can be found back in the following formula using random sets

$$\underline{\mathbb{E}}(h) = \int_0^{F(b_n)} \min_{b_i \in A_\gamma} (h(a_{*\gamma}), h(b_i), h(a_\gamma^*)) d\gamma + \int_{F(b_n)}^1 h(a_{*\gamma}) d\gamma,$$

- Optimal distribution F is a succession of vertical jumps (prob. mass concentrated on b_i) and of horizontal jumps (to avoid highest values of h)

perspectives

- Pursue investigations on multivariate case, by generalizing existing results to more general functions and to n dimensional case and by exploring the case of epistemic independence
- Design efficient algorithms to make good approximations (i.e. how to find good values for levels α_i with functions having many extrema ?)
- Study various ways to integrate information about dependencies, e.g. by using copulas or adding constraints to LP problems.